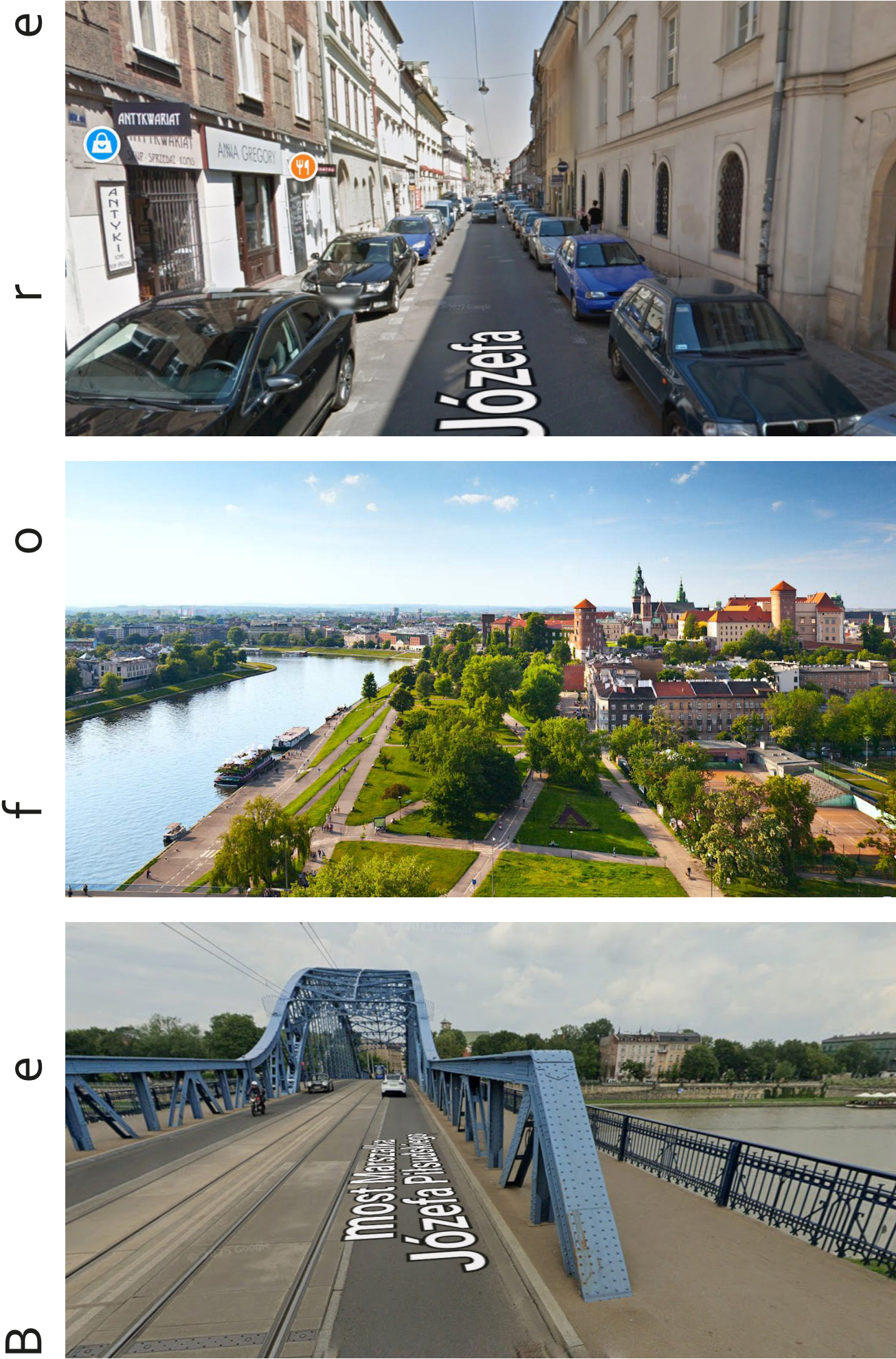
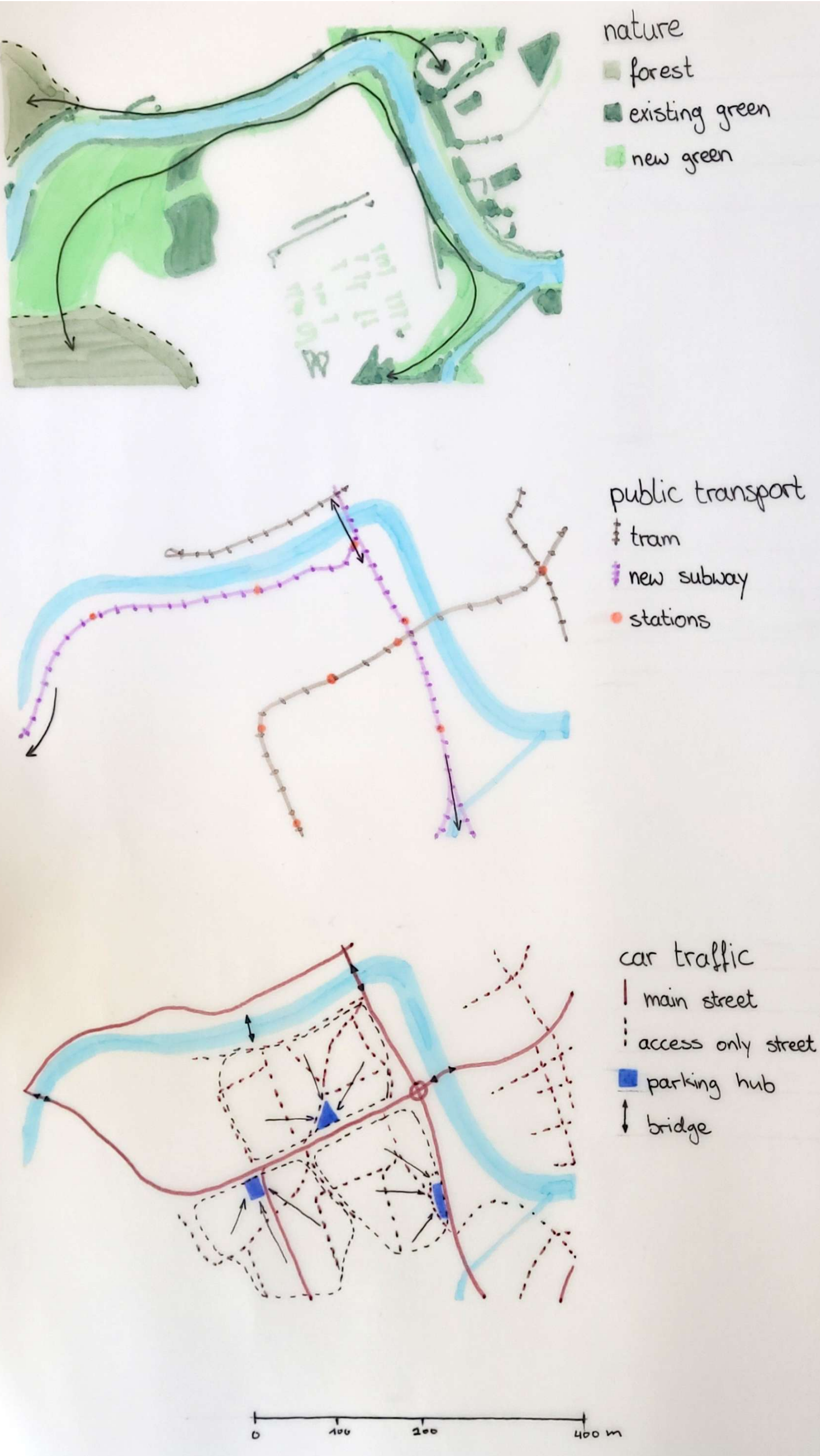


Krakov Strategy

Mobility and Green Infrastructure Masterplan

Anja Bader & Yasmin Sherif | Urbanismo 1 | Group C | 2025/26



The proposed masterplan for Krakow envisions a transformation of the city's mobility system into a sustainable, people oriented network. The strategy limits car traffic to the main arterial roads, freeing most secondary and local streets to become pedestrian-oriented zones. These new walkable areas would remain accessible for residents, delivery vehicles, and emergency services, ensuring functionality without compromising the human-scale character of the neighborhoods. The reduction of through-traffic aims to create safer, quieter, and cleaner urban spaces, supporting active mobility and social life in public areas. Each residential district will include a main parking building, designed as a shared place for local residents and for commuters using nearby „park and ride“ facilities. A new metro line is introduced to complement the existing tram system, improving accessibility and reducing dependence on private cars. Together, the tram, metro, and pedestrian networks form a



cohesive mobility system that prioritizes efficiency, environmental responsibility, and the quality of urban life. Former highway bridges crossing the river will be repurposed exclusively for trams, pedestrians, and cyclists. This symbolic and functional shift from car dominance to shared urban mobility, illustrates Krakow's commitment to a greener, more inclusive future. The overall vision redefines movement and space within the city, integrating nature, transport, and community into a balanced urban ecosystem. The river becomes a central element of the plan. Both a connector between districts and a continuous green corridor that links the surrounding forests with inner city parks and open spaces. This blue-green infrastructure strengthens Krakow's ecological network, enhances biodiversity, and provides recreational routes along the water for pedestrians and cyclists.



